

4. Consider the differential equation:

$$(*) \quad a \frac{d^2u}{dx^2} + b \frac{du}{dx} = f(x) \text{ for } x \in (0, 2\pi),$$

where  $a, b > 0$ . Assume  $u$  and  $f$  are periodically extended to  $\mathbb{R}$ . Divide the interval  $[0, 2\pi]$  into  $n$  equal portions, where  $n = 2^l$  for some  $l > 10$ . Let  $x_j = \frac{2\pi j}{n}$  for  $j = 0, 1, 2, \dots, n - 1$ .

Let  $\mathbf{u} = (u(x_0), u(x_1), \dots, u(x_{n-1}))^T$  and  $\mathbf{f} = (f(x_0), f(x_1), \dots, f(x_{n-1}))^T$ .

Let  $\mathcal{D}_1$  and  $\mathcal{D}_2$  be two  $n \times n$  matrices, which are defined in such a way that:

$$(\mathcal{D}_1 \mathbf{u})_j = \frac{u(x_{j+4}) - u(x_{j-4})}{8h} \quad \text{and} \quad (\mathcal{D}_2 \mathbf{u})_j = \frac{u(x_{j+4}) - 2u(x_j) + u(x_{j-4})}{16h^2}.$$

for  $j = 0, 1, 2, \dots, n - 1$  and  $h = \frac{2\pi}{n}$ .

- (a) Using Taylor expansion, explain why  $\mathcal{D}_1$  and  $\mathcal{D}_2$  approximate  $\frac{d}{dx}$  and  $\frac{d^2}{dx^2}$  respectively. Hence, deduce that the differential equation  $(*)$  can be discretized as:

$$(**) \quad a\mathcal{D}_2 \mathbf{u} + b\mathcal{D}_1 \mathbf{u} = \mathbf{f}.$$

- (b) Let  $\mathbf{u} = \sum_{k=0}^{n-1} \hat{u}_k e^{\overrightarrow{ikx}}$  and  $\mathbf{f} = \sum_{k=0}^{n-1} \hat{f}_k e^{\overrightarrow{ikx}}$ , where  $\hat{u}_k, \hat{f}_k \in \mathbb{C}$ . If  $\mathbf{u}$  satisfies  $(**)$ , show that

$$(a\lambda_k + b\tilde{\lambda}_k)\hat{u}_k = \hat{f}_k \text{ for some } \lambda_k \text{ and } \tilde{\lambda}_k,$$

for  $k = 0, 1, 2, \dots, n - 1$ . What are  $\lambda_k$  and  $\tilde{\lambda}_k$ ? Please explain your answer with details.

- (c) Let  $\mathbf{u}^*$  be one of the solutions of  $(**)$ . What is the general solution of  $(**)$ ? Please show and explain your answer with details.

$$\begin{aligned}
 (b). \quad (\mathcal{D}_1 e^{\overrightarrow{ikx}})_j &= \frac{e^{ikx_{j+4}} - e^{-ikx_{j-4}}}{8h} \\
 &= \frac{e^{ik4h} - e^{-ik4h}}{8h} e^{ikx_j} \\
 &= \frac{1}{8h} \left( \cos 4kh + i \sin 4kh \right. \\
 &\quad \left. - \cos 4kh + i \sin 4kh \right) e^{ikx_j} \\
 &= \frac{i}{4h} \sin 4kh e^{ikx_j} \\
 &\quad \underline{\underline{\tilde{\lambda}_k}}
 \end{aligned}$$

$$\begin{aligned}
 (D_2 \vec{e}^{ikx})_j &= \frac{e^{ikx_{j+4}} - 2e^{ikx_j} + e^{ikx_{j-4}}}{16h^2} \\
 &= \frac{1}{(6h)^2} \left( e^{i4kh} - 2 + e^{-i4kh} \right) e^{ikx_j} \\
 &= \frac{1}{(6h)^2} (2\cos 4kh - 2) e^{ikx_j} \\
 &= \frac{1}{8h^2} (\cos^2 2kh - \sin^2 2kh) e^{ikx_j} \\
 &= \frac{1}{4h^2} \underbrace{\sin^2 2kh}_{\lambda_k} e^{ikx_j}
 \end{aligned}$$

(c).  $\vec{u}^*$  is a solution to the discrete ODE.

$$A := a D_2 + b D_1$$

discrete ODE:

$$a D_2 \vec{u} + b D_1 \vec{u} = f$$

$$\Leftrightarrow A \vec{u} = f.$$

If  $\vec{u}^*$  is a solution,

then  $\vec{u}^* + \vec{u}_0$  is also a solution,

where  $\tilde{u}_0 \in N(A)$ .

Note the null space

is spanned by eigenvectors with zero eigenvalues.

eigenvalues of  $A$  is given by

$$a \lambda_k + b \tilde{\lambda}_k$$

$$= \underbrace{a \cdot \frac{1}{4h} \sin^2 2kh}_{\text{Re}} + \underbrace{b \frac{i}{4h} \sin 4kh}_{\text{Im}}$$

$$= 0 \quad \text{iff} \quad \text{Re} = 0 \quad \text{and} \quad \text{Im} = 0.$$

$$0 = \frac{a}{4h} \sin^2 2kh$$

$$\Leftrightarrow 0 = \sin\left(\frac{4\pi}{n}k\right), k = 0, 1, \dots, n-1$$

$$\Leftrightarrow k = 0 \text{ or } \frac{n}{4} \text{ or } \frac{2}{4}n \text{ or } \frac{3}{4}n. \quad \leftarrow n = 2^l$$

$$0 = \frac{b}{4n} \sin 4kn$$

$$\Leftrightarrow 0 = \sin\left(\frac{f\pi}{n}k\right), \quad k = 0, 1, \dots, n-1$$

$$k = \frac{m}{f}n, \quad m = 0, 1, \dots, 7.$$

Real Part and Imaginary Part both are zero if

$$k = \frac{m}{f}n, \quad m = 0, 1, 2, 3.$$

$$N(A) = \text{Span} \left\{ \overrightarrow{e^{i0x}}, \overrightarrow{e^{i\frac{n}{4}\pi}}, \overrightarrow{e^{i\frac{n}{2}\pi}}, \overrightarrow{e^{i\frac{3}{4}n\pi}} \right\}$$

$\therefore$  a general solution is:

$$\begin{aligned} u = & \vec{u}^* + c_0 \overrightarrow{e^{i0x}} + c_1 \overrightarrow{e^{i\frac{n}{4}\pi}} \\ & + c_2 \overrightarrow{e^{i\frac{n}{2}\pi}} + c_3 \overrightarrow{e^{i\frac{3}{4}n\pi}}. \end{aligned}$$

5. Let  $A$  be a  $n \times n$  complex matrix given by:

$$A = \begin{pmatrix} c_0 & c_1 & c_2 & \cdots & c_{n-1} \\ c_{n-1} & c_0 & c_1 & \cdots & c_{n-2} \\ c_{n-2} & c_{n-1} & c_0 & \cdots & \vdots \\ \ddots & \ddots & \ddots & \ddots & \ddots \\ c_1 & c_2 & \cdots & c_{n-1} & c_0 \end{pmatrix}$$

- (a) Show that  $\overrightarrow{e^{ikx}}$  is an eigenvector of  $A$  corresponding to an eigenvalue  $\mu_k$  for  $k = 0, 1, 2, \dots, n-1$ . What is  $\mu_k$ ? Please show all your steps in details.

Periodically extend  $c_\ell$ :

$$c_{\ell+n} = c_{\ell-n} = c_\ell.$$

$$\begin{aligned} (A \overrightarrow{e^{ikx}})_j &= \sum_{l=0}^{n-1} c_{\ell-j} e^{ikhl} \\ &= \left( \sum_{l=0}^{n-1} c_{\ell-j} e^{ikh(l-j)} \right) e^{ikhj} \\ &= \sum_{l=-j}^{n-1-j} c_\ell e^{ikh\ell} \cdot e^{ikhj} \\ &= \left( \sum_{l=0}^{n-1-j} + \sum_{l=-j}^{-1} \right) c_\ell e^{ikh\ell} \cdot e^{ikhj} \end{aligned}$$


$$\left. \begin{aligned} \sum_{l=-j}^{-1} (e e^{ikhl}) &= \sum_{l=-j}^{-1} (e_{l+n} e^{ikh(l+n)}) \\ &= \sum_{l=n-j}^{n-1} (e e^{ikhl}) \end{aligned} \right)$$



$$= \left( \sum_{l=0}^{n-1-j} + \sum_{l=n-j}^{n-1} \right) (e e^{ikhl} e^{ikhij})$$

$$= \underbrace{\left( \sum_{l=0}^{n-1} (e e^{ikhl}) \right)}_{\text{mk.}} e^{ikhij}$$

mk.

- (b) Suppose  $A\mathbf{x} = \mathbf{f}$ , where  $\mathbf{x}$  and  $\mathbf{f}$  are both complex vectors in  $\mathbb{C}^n$ . Using (a), show that:

$$\begin{pmatrix} \mu_0 \\ \mu_1 \\ \vdots \\ \mu_{n-1} \end{pmatrix} \otimes \text{DFT}(\mathbf{x}) = \text{DFT}(\mathbf{f})$$

where

$$\begin{pmatrix} a_0 \\ a_1 \\ \vdots \\ a_{n-1} \end{pmatrix} \otimes \begin{pmatrix} b_0 \\ b_1 \\ \vdots \\ b_{n-1} \end{pmatrix} = \begin{pmatrix} a_0 b_0 \\ a_1 b_1 \\ \vdots \\ a_{n-1} b_{n-1} \end{pmatrix}.$$

Please explain your answer with details.

$\mathbf{B}_1$  is DFT on  $\vec{\mathbf{x}}$  and  $\vec{\mathbf{f}}$ ,

$$A \vec{\mathbf{x}} = \vec{\mathbf{f}}$$

$$\Rightarrow A \left( \sum_{j=0}^{n-1} \hat{x}_j \overrightarrow{e^{ijx}} \right) = \sum_{j=0}^{n-1} \hat{f}_j \overrightarrow{e^{ijx}}$$

$$\Rightarrow \sum_{j=0}^{n-1} \hat{x}_j (A \overrightarrow{e^{ijx}}) = \sum_{j=0}^{n-1} \hat{f}_j \overrightarrow{e^{ijx}}$$

$$\Rightarrow \sum_{j=0}^{n-1} \hat{x}_j \mu_j \overrightarrow{e^{ijx}} = \sum_{j=0}^{n-1} \hat{f}_j \overrightarrow{e^{ijx}}$$

Linear Independence of  $\{\overrightarrow{e^{ijx}}\}$

$$\Rightarrow \hat{x}_j \mu_j = \hat{f}_j \quad \forall j = 0, 1, \dots, n-1.$$

## Numerical Iterative Methods

In general, an iterative method for solving some problem  $f(x) = 0$  is defined by:

$$x^{k+1} = \Phi(x^k), k = 0, 1, \dots$$

If  $x^*$  is a solution,

$$\text{we need } x^* = \Phi(x^*).$$

Now, we consider

$$\text{the problem } Ax = b,$$

$$\text{iterative scheme } x^{k+1} = Mx^k + f,$$

$$A, B \in \mathbb{R}^{n \times n}, b, f \in \mathbb{R}^n.$$

$$\begin{aligned} x^{k+1} &= Mx^k + f \\ - \quad x^* &= Mx^* + f \\ \hline x^{k+1} - x^* &= M(x^k - x^*) \end{aligned}$$

Error vector :  $\vec{e}^{k+1} = M \vec{e}^k$

$$= M(M \vec{e}^{k-1})$$

$$\vdots$$

$$= M^{k+1} \vec{e}_0$$

Suppose  $M \in \mathbb{R}^{n \times n}$  has  $n$  linearly independent eigenvectors.

$\lambda_i$ : eigenvalues,  $\vec{u}_i$ : eigenvectors

Suppose  $|\lambda_1| = \max_i \{ |\lambda_i| \}$ .

$$\begin{aligned} \vec{e}_k &= M^k \vec{e}_0, \quad \vec{e}_0 = \sum_{j=0}^{n-1} a_j \vec{u}_j \\ &= \sum_{j=0}^{n-1} \lambda_1^k a_j \vec{u}_j. \end{aligned}$$

$$= \lambda_1^k \left( \sum_{j=0}^{n-1} \left( \frac{\lambda_1}{\lambda_1} \right)^k a_j \vec{u}_j \right) \rightarrow 0 \text{ if } |\lambda_1| < 1.$$

So, we have if  $\frac{\text{abs. of } \lambda_{\max}}{\text{spectral radius } \rho} < 1$ ,

the iterative scheme converges

## Jacobi / Gauss - Seidel Method

For  $A \vec{x} = b$ ,

$$A = L + D + U$$

$$\text{Jacobi: } \vec{x}_{k+1} = D^{-1}(-L-U)\vec{x}_k + D^{-1}\vec{f}.$$

$$\begin{aligned} & D^{-1}(-L-U)\vec{x}_k^* + D^{-1}\vec{f} \\ &= D^{-1}(-L-D-U)\vec{x}_k^* + D^{-1}D\vec{x}_k^* + D^{-1}\vec{f} \\ &= D^{-1}(-A\vec{x}_k^* + \vec{f}) + \vec{x}_k^* \\ &= \vec{x}_k^* \end{aligned}$$

$$(7-5): \quad \vec{x}^{k+1} = - (L+D)^{-1} U \vec{x}^k + (L+D)^{-1} \vec{f}$$

$$= - (L+D)^{-1} U \vec{x}^* + (L+D)^{-1} \vec{f}$$

$$= - (L+D)^{-1} (L+D+U) \vec{x}^* + (L+D)^{-1} (L+D) \vec{x}^* \\ + (L+D)^{-1} \vec{f}$$

$$= - (L+D)^{-1} (-A \vec{x}^* + \vec{f}) + \vec{x}^*$$

$$= \vec{x}^*$$

## Example

$$A = \begin{bmatrix} 5 & -2 & 3 \\ -3 & 9 & 1 \\ 2 & -1 & -7 \end{bmatrix}$$

Jacobi :  $M_J = \begin{bmatrix} 0, & 2/5, & -3/5 \\ 1/3, & 0, & -1/4 \\ 2/7, & 1/7, & 0 \end{bmatrix}$

G-S :  $M_{GS} = \begin{bmatrix} 0, & 2/5, & -3/5 \\ 0, & 2/15, & -14/45 \\ 0, & 2/21, & -8/63 \end{bmatrix}$

To study the convergence,

We can compute eigenvalues:

$$(M_J : 0.22, -0.11 - 0.24i, -0.11 + 0.24i)$$

$$(M_{GS} : 0, 0.0032 - 0.11i, 0.0032 + 0.11i)$$

Or consider Gershgorin Circle Theorem.

## Exercise

Consider

$$A = \begin{bmatrix} 4 & 1 & 1 \\ 2 & -4 & 0 \\ 0 & -8 & 6 \end{bmatrix}$$

Find  $M_3$ ,  $M_{\text{GS}}$

and their spectral radius.

Are Jacobi or Gauss-Seidel  
methods converge?

Solution :

$$M_J = \begin{bmatrix} 0, -\frac{1}{4}, -\frac{1}{4} \\ \frac{2}{3}, 0, 0 \\ 0, -\frac{4}{3}, 0 \end{bmatrix}$$

eigenvalues :  $0.38, -0.19 - 0.40i$  ;  
 $-0.19 + 0.40i$  ;

$$\rho(M_J) = 0.44$$

$$M_{GS} = \begin{bmatrix} 0, -\frac{1}{4}, -\frac{1}{4} \\ 0, -\frac{1}{18}, -\frac{1}{18} \\ 0, \frac{2}{27}, \frac{2}{27} \end{bmatrix}$$

eigenvalue =  $0, 0, 0.0185$

$$\rho(M_{GS}) = 0.0185$$